# PLANE CONFIGURATIONS IN A FLOW OF A PERFECT GAS WITH A MAXIMUM CRITICAL MACH NUMBER 

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The problems in the construction of bodies which, satisfying some geometric limitations, are exposed to a plane symmetric flow of a perfect (inviscid and heat-nonconducting) gas with a maximum critical Mach number $\mathrm{M}_{*}$ are considered. Solutions are found by a numericalanalytical method with the use of the variables of the velocity hodograph. The Mach number $\mathrm{M}_{*}$ is found as a function of the geometric characteristics of the sought bodies on the basis of approximation of numerical data.

The critical Mach number $\mathrm{M}_{*}$, i.e., the minimum free-stream Mach number responsible for a flow velocity equal to the critical value, is one of the most important characteristics of bodies exposed to a gas flow. Of practical interest are bodies that satisfy some geometric restrictions and allow the maximum possible value of $\mathrm{M}_{*}$. As bodies of this class, they do not experience the wave drag within the maximum range of free-stream velocities. We call these bodies optimal or optimal relative to $\mathrm{M}_{*}$.

The structure of plane symmetrical optimal bodies and optimal bodies of revolution in a perfect gas flow was studied in [1, 2]. It was established that, for a wide range of geometric restrictions, the contours of optimal bodies consist of straight sections and sections on which the gas velocity equals the critical value. The shape of optimal bodies depends on the properties of a gas flow. An ideal perfect gas with the ratio of specific heats $\gamma=1.4$ is called an air-like gas.

Various numerical and numerical-analytical methods were used in [3-6] to solve some problems of construction of plane symmetrical optimal bodies in an air-like gas flow. The results obtained were presented as numerical data and plots.

In the present work, similar problems are studied in more detail using a numerical-analytical method proposed in [ 7,8 ], which was previously used by the authors to study optimal bodies of revolution relative to $M_{*}[9,10]$. The formulas presented describe the dependence of $M_{*}$ on the basic geometric characteristics of optimal bodies, which were obtained as a result of approximation of numerical data.

1. We consider an attached infinite steady-state potential ideal gas flow around cylindrical bodies with a plane of symmetry $\Omega$. In the plane $z=x+i y$ perpendicular to the generatrices of the cylindrical surface of the body, the flow is assumed to be symmetric about the $x$ axis, which belongs to $\Omega$ and is parallel to the free-stream velocity vector.

Let $L_{1}$ and $H_{1}$ be the lengths of the projections of the body onto the $x$ and $y$ axes, respectively, $S_{1}$ is the area of the body cut by the $z$ plane, and $\theta_{w}$ is the angle of inclination of the velocity vector to the $x$ axis on the surface of the body.

Problem A. Among symmetrical bodies which satisfy one of the conditions

$$
\begin{equation*}
H_{1} / L_{1} \geqslant k_{0}, \quad S_{1} / L_{1}^{2} \geqslant l_{0} \tag{1.1}
\end{equation*}
$$

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Fig. 1
and the condition

$$
\begin{equation*}
\max \left|\theta_{w}\right| \leqslant \theta_{0} \leqslant \pi / 2 \tag{1.2}
\end{equation*}
$$

( $k_{0}, l_{0}$, and $\theta_{0}$ are given constants, and $k_{0}$ and $l_{0}<\tan \theta_{0}$ ), we have to find a body that ensures the maximum value of $\mathrm{M}_{*}$.

Problem $A_{0}$ is obtained from the previous problem by removing condition (1.2). It was considered for the first time by Gilbarg and Shiffman [1]. According to [1], in the $z$ plane the contour of a symmetrical body, which satisfies one of conditions (1.1) and ensures the maximum $\mathrm{M}_{*}$, consists of two equal straight sections perpendicular to the $x$ axis and to the streamlines that connect these sections and on which the gas velocity is equal to the critical value. In other words, problem $A_{0}$ reduces to the problem of a symmetrical flow past a flat plate in accordance with the Ryabushinskii pattern [11], with the critical velocity on the free surface. Similarly, problem A reduces to the problem of a symmetrical flow around a wedge with half-angle $\theta_{0}$ in accordance with the same scheme. (The solution of problem A for $\theta_{0}=\pi / 2$ coincides with that of problem $\mathrm{A}_{0}$.)

Some results of a numerical solution of problem $\mathrm{A}_{0}$ and a problem similar to problem A can be found in [3, 4] and [5], respectively.

Problem B. Let the section of the body by the $z$ plane be a rectangular half-band of width $H_{2}$, which is symmetric about the $x$ axis. It is required to deform the head part (adjacent to the end face) of the body so that the resultant symmetrical body had an attached flow with the maximum possible value of $\mathrm{M}_{*}$ if condition (1.2) is satisfied together with one of the conditions

$$
\begin{equation*}
L_{2} / H_{2} \leqslant m_{0}, \quad S_{2}^{\prime} / H_{2}^{2} \leqslant n_{0} . \tag{1.3}
\end{equation*}
$$

Here $L_{2}$ is the length of the head part (subjected to deformation) of the body, $S_{2}^{\prime}$ is the cross sectional area lost because of deformation, and $m_{0}$ and $n_{0}$ are some prescribed constants [ $m_{0}>(1 / 2) \cot \theta_{0}$ and $\left.n_{0}>(1 / 4) \cot \theta_{0}\right]$. Thus, we obtain $S_{2}^{\prime}=L_{2} H_{2}-S_{2}$, where $S_{2}$ is the area of the head part of the body. The inequalities (1.3) limit the loss of the "capacity" of the initially existing volume.

Note that the head part of the body can be equally readily considered to be the rear part.
Using the comparative theorem [1, 2], we can easily show that the construction of an optimal body that corresponds to the conditions of problem B reduces to the solution of the problem of a symmetric flow around a wedge with a half-angle $\theta_{0}$ according to the Joukowski-Roshko pattern [11], with the critical velocity on the free surface.

Some results of the solution of the problem of contouring of the optimal, in terms of $M_{*}$, head or tail part of a plane symmetrical semi-infinite body with given values of $L_{2}, H_{2}$, and $\theta_{0}$ can be found in [6].
2. In the plane $z=x+i y$, we consider a steady subsonic vortex-free flow of an ideal gas, which is
symmetric about the $x$ axis, around a wedge with the half-angle $\theta_{0} \leqslant \pi / 2$ with the use of the Ryabushinskii and Joukowski-Roshko patterns. The left part of Fig. 1 shows flow regions that correspond to these schemes and are located above the $x$ axis. Here $b c$ and $g h$ are the walls of the real and fictitious wedges, $c d g$ and $c e$ are the free surfaces, $e a$ is the half-line parallel to the $x$ axis, $a$ is the infinitely distant point, and the point $d$ lies on the $y$ axis, which is an additional axis of symmetry for the flow according to the Ryabushinskii pattern. In accordance with the notation in Sec. 1, the distance between the points $b$ and $h$ is $L_{1}$, the ordinate of the point $d$ is $H_{1} / 2, S_{1} / 2$ is the area bounded by the contour bcdgh and the $x$ axis, $S_{2} / 2$ is the area bounded by the contour bce, the $x$ axis, and the $y$ axis passing through the point $e$, and $L_{2}$ and $H_{2} / 2$ are the lengths of the projections of the contour bce onto the $x$ and $y$ axes, respectively.

Let $\lambda$ be the reduced velocity, $M$ is the Mach number, $\theta$ is the angle of inclination of the velocity to the $x$ axis, $\lambda_{a}$ and $\lambda_{c}$ are the values of $\lambda$ at an infinitely distant point and on the free surface, respectively $\left(\lambda_{a} \leqslant \lambda_{c} \leqslant 1\right), M_{a}$ and $M_{c}$ are the values of $M$ for $\lambda=\lambda_{a}$ and $\lambda=\lambda_{c}$, and $\tau=\lambda / \lambda_{a}$ and $\tau_{0}=\lambda_{c} / \lambda_{a}$. The right part of Fig. 1 shows the regions $\Sigma=\left\{(\tau, \theta) \mid 0<\tau<\tau_{0}, 0<\theta<\theta_{0}\right\}$ in the plane ( $\tau, \theta$ ) that correspond to the top left quarter of the flow region according to the Ryabushinskii pattern and to the upper half of the flow region according to the Joukowski-Roshko pattern. The section $B B_{1}$ corresponds to the point of flow bifurcation $b$ and the points $A, C, D$, and $E$ correspond to the points $a, c, d$, and $e$, respectively.

We introduce the stream function $\psi$ with the use of the relations $\tau \nu \cos \theta=\psi_{y}$ and $\tau \nu \sin \theta=-\psi_{x}$. Here $\nu=\rho / \rho_{0}, \rho$ is the density of the gas, $\rho_{0}$ is the value of $\rho$ in the frozen flow, the subscripts refer to partial derivatives. Under the above assumptions, the stream function $\psi$ in the region $\Sigma$ satisfies the Chaplygin equation

$$
\begin{equation*}
L \psi=\left(1-\mathrm{M}^{2}\right) \psi_{\theta \theta}+\tau^{2} \psi_{\tau \tau}+\tau\left(1+\mathrm{M}^{2}\right) \psi_{\tau}=0 \tag{2.1}
\end{equation*}
$$

For the flow according to the Ryabushinskii pattern, we have $\psi=0$ on $A B B_{1} C D$ and $\psi_{\theta}=0$ on $A D$. For the flow according to the Joukowski-Roshko pattern, we have $\psi=0$ on $A B B_{1} C E A$.

We consider the dependences $\nu(\tau)$ and $M(\tau)$, determined by the gas properties, to be known differentiable functions, which are analytical in the vicinity of the point $\tau=1\left(\lambda=\lambda_{a}\right)$. The coefficients of Eq. (2.1) can be expanded into power series with respect to $\zeta=\tau-1$ :

$$
\begin{gather*}
\tau^{2}=1+2 \zeta+\zeta^{2}, \quad 1-\mathrm{M}^{2}=\sum_{k=0}^{\infty} p_{k} \zeta^{k}, \quad \tau\left(1+\mathrm{M}^{2}\right)=\sum_{k=0}^{\infty} q_{k} \zeta^{k} \\
p_{0}=1-\mathrm{M}_{a}^{2}, \quad p_{k}=-\left.\frac{1}{k!} \frac{d^{k} \mathrm{M}^{2}}{d \tau^{k}}\right|_{\tau=1}, \quad k=1,2, \ldots,  \tag{2.2}\\
q_{0}=2-p_{0}, \quad q_{1}=q_{0}-p_{1}, \quad q_{k}=-p_{k-1}-p_{k}, \quad k=2,3, \ldots
\end{gather*}
$$

We represent the stream function $\psi$ as $\psi=\psi^{0}+\chi$, where $\psi^{0}$ is a function that describes the behavior of $\psi$ in the vicinity of the singular point $A$. We introduce the variables $\sigma$ and $\omega$ :

$$
\begin{equation*}
\sigma=\left(\theta^{2}+\alpha^{2} \zeta^{2}\right)^{1 / 2}, \quad \omega=\arctan \left(\frac{\theta}{\alpha \zeta}\right), \quad \alpha=\sqrt{1-\mathrm{M}_{a}^{2}} \tag{2.3}
\end{equation*}
$$

According to (2.3) and $\zeta=\alpha^{-1} \sigma \cos \omega$, we have

$$
\begin{equation*}
\sigma_{\theta}=\sin \omega, \quad \sigma_{\tau}=\alpha \cos \omega, \quad \omega_{\theta}=\sigma^{-1} \cos \omega, \quad \omega_{\tau}=-\alpha \sigma^{-1} \sin \omega . \tag{2.4}
\end{equation*}
$$

We seek the function $\psi^{0}$ in the form of an asymptotic expansion with respect to the small parameter $\sigma$. We assume that

$$
\begin{equation*}
\psi^{0}=\psi_{1}+\psi_{2}+\ldots, \quad \psi_{k}=h_{k}(\sigma) f_{k}(\omega) ; \quad h_{k+1}(\sigma) / h_{k}(\sigma) \rightarrow 0, \quad \sigma \rightarrow 0, \quad k=1,2, \ldots \tag{2.5}
\end{equation*}
$$

and require that the conditions

$$
\begin{equation*}
\psi_{1}>0, \quad 0<\omega<\pi \tag{2.6}
\end{equation*}
$$

for both flow patterns and also the conditions

$$
\begin{equation*}
\psi_{k}=0, \quad \omega=0, \pi, \quad k=1,2, \ldots \tag{2.7}
\end{equation*}
$$

for the flow according to the Joukowski-Roshko pattern and the conditions

$$
\begin{equation*}
\psi_{k}=0, \quad \omega=\pi ; \quad \psi_{k \theta}=0, \quad \omega=0, \quad k=1,2, \ldots \tag{2.8}
\end{equation*}
$$

for the flow according to the Ryabushinskii pattern be satisfied.
We represent the main term in the expansion (2.5) in the form $\psi_{1}=\sigma^{-n} f_{1}(\omega)(n=$ const, $n>0)$. Assuming that $\zeta=\alpha^{-1} \sigma \cos \omega$ in (2.2) and using (2.4), we can show that, for $\psi_{1}=\sigma^{-\pi} f_{1}(\omega)$,

$$
L \psi_{1}=R_{1}+\Delta R_{1}, \quad R_{1}=\alpha^{2} \sigma^{-n-2}\left(n^{2} f_{1}+f_{1}^{\prime \prime}\right), \quad \Delta R_{1}=O\left(\sigma^{-n-1}\right)
$$

Equating $R_{1}$, the main term in the expansion of $L \psi_{1}$ with respect to powers of $\sigma$, to zero and taking into account (2.6) and (2.7) or (2.6) and (2.8), we obtain the boundary-value problem for the function $f_{1}(\omega)$. In particular, for the flow according to the Joukowski-Roshko pattern, the following boundary-value problem is obtained:

$$
\begin{equation*}
n^{2} f_{1}+f_{1}^{\prime \prime}=0, \quad f_{1}(0)=f_{1}(\pi)=0, \quad f_{1}(\omega)>0, \quad 0<\omega<\pi, \quad n>0 . \tag{2.9}
\end{equation*}
$$

It is easy to see that there is a unique (to within constant factor at $f_{1}$ ) solution of problem (2.9): $n=1$ and $f_{1}=\sin \omega$. Thus, we obtain that $\psi_{1}=\sigma^{-1} \sin \omega$.

In substituting $\psi=\psi_{1}=\sigma^{-1} \sin \omega$ into (2.1), the terms of the order of $\sigma^{-3}$, which result from differentiation of $\psi_{1}$, cancel each other, and the residual of the order of $\sigma^{-2}$ is left. We seek the term of the expansion (2.5) that follows $\psi_{1}$ in the form $\psi_{2}=f_{2}(\omega)$ by requiring that, after the substitution of $\psi=\psi_{1}+\psi_{2}$ into (2.1), the terms of the order of $\sigma^{-2}$ cancel each other, and the residual of the order of $\sigma^{-1}$ be left. Taking into account (2.7), we obtain the following boundary-value problem for $f_{2}(\omega)$ :

$$
\begin{gather*}
\alpha^{2} f_{2}^{\prime \prime}=\delta_{1} \sin \omega \cos \omega+\delta_{2} \sin ^{3} \omega \cos \omega, \quad \delta_{1}=6 p_{1} \alpha^{-1}-12 \alpha+2 \alpha q_{0},  \tag{2.10}\\
\delta_{2}=16 \alpha-8 p_{1} \alpha^{-1}, \quad f_{2}(0)=f_{2}(\pi)=0 .
\end{gather*}
$$

There exists the unique solution of problem (2.10):

$$
\psi_{2}=f_{2}(\omega)=-\frac{1}{16}\left(2 \delta_{1}+\delta_{2}\right) \alpha^{-2} \sin 2 \omega+\frac{1}{128} \delta_{2} \alpha^{-2} \sin 4 \omega .
$$

It is natural to seek the function $\psi_{3}$ in the form $\psi_{3}=\sigma f_{3}(\omega)$ by requiring that, after the substitution of $\psi=\psi_{1}+\psi_{2}+\psi_{3}$ into (2.1), the terms of the order of $\sigma^{-1}$ cancel each other, and the residual of the order of unity be left. In this case, we obtain the following boundary-value problem for $f_{3}$ :

$$
\begin{equation*}
f_{3}+f_{3}^{\prime \prime}=F_{3}, \quad f_{3}(0)=f_{3}(\pi)=0 \tag{2.11}
\end{equation*}
$$

( $F_{3}$ is a known function of $\omega$ ). Since the function $f=\sin \omega$ satisfies the conditions $f+f^{\prime \prime}=0$ and $f(0)=$ $f(\pi)=0$, the solution of problem (2.11) is found to an accuracy of the term $q \sin \omega$, where $q=$ const. The resultant indeterminacy shows that the behavior of $\psi$ in the vicinity of the single point $A$ can be refined only with allowance for the complete boundary conditions for this function.

We now pass to the flow according to the Ryabushinskii pattern. Assuming that $\psi_{1}=\sigma^{-n} f_{1}(\omega)$, equating to zero the main term in the expansion of $L \psi_{1}$ with respect to powers of $\sigma$, and taking into account (2.6) and (2.8), we obtain the boundary-value problem

$$
\begin{equation*}
n^{2} f_{1}+f_{1}^{\prime \prime}=0, \quad f_{1}(\pi)=f_{1}^{\prime}(0)=0, \quad f_{1}(\omega)>0, \quad 0<\omega<\pi, \quad n>0 . \tag{2.12}
\end{equation*}
$$

The solution of problem (2.12) has the form $n=1 / 2$ and $f_{1}=\cos (\omega / 2)$. Thus, $\psi_{1}=\sigma^{-1 / 2} \cos (\omega / 2)$.
In finding the function $\psi_{2}$ there arises an indeterminacy similar to that described above for the function $\psi_{3}$ in the flow problem according to the Joukowski-Roshko pattern.
3. Knowing the function $\psi^{0}$, we can pass to the solution of the boundary-value problem for $\psi$, using the finite-difference method. Two approaches are possible. The first approach is based on finding the function $\chi=\psi-\psi^{0}$ from the solution of the corresponding boundary-value problem for the equation $L \chi=-L \psi^{0}$.

Using this approach, we can continue the procedure for finding the function $\psi^{0}$ that satisfies the condition $L \psi^{0} \rightarrow 0$ for $\sigma \rightarrow 0$ and the boundary conditions of the corresponding problem on the sections of the boundary adjacent to the singular point $A$ (the ambiguity of the solution is not important here). The second approach is based on the idea that the function $\psi$ is close to $\psi^{0}$ in the vicinity of the point $A$. In this approach, the values of $\psi^{0}$ on a certain rectangular broken line, which separates the vicinity of the point $A$ from the other part of the domain $\Sigma$, are used as the boundary conditions of the function $\psi$ in solving the corresponding boundary-value problem for the equation $L \psi=0$. Calculations demonstrated greater simplicity and reliability of the second approach, which was used to obtain the results of the present paper.

When the values of $\lambda_{a}$ and $\lambda_{c}$ are close to each other, the gradients of $\psi$ near the sections $A D$ and $A E$ are large. This makes it necessary to transform the independent variables in a numerical solution of the problem. In particular, the following transformations [12, § 5.6], which transform $\Sigma$ into $\Sigma_{1}=\{(\xi, \eta) \mid 0<\xi<$ 1. $0<\eta<1\}$, are convenient:

$$
\begin{align*}
& \xi=F\left(1+\beta_{1}, \tau / \tau_{0}\right), \quad \eta=1-F\left(1+\beta_{2}, 1-\theta / \theta_{0}\right),  \tag{3.1}\\
& F(x, y)=\ln [(x+y) /(x-y)]\{\ln [(x+1) /(x-1)]\}^{-1}
\end{align*}
$$

(the parameters $\beta_{1}$ and $\beta_{2}$ are small positive numbers).
In the domain $\Sigma_{1}$, we used the finite-difference scheme with a five-point approximation on a uniform rectangular grid. The method of sequential upper relaxation is used for its realization.

After determining the function $\psi(\tau, \theta)$, the transition to the physical plane is performed using the formulas

$$
\begin{equation*}
\nu \tau^{2} z_{\tau}=\left[\left(\mathrm{M}^{2}-1\right) \psi_{\theta}+i \tau \psi_{\tau}\right] \exp (i \theta), \quad \nu \tau z_{\theta}=\left[\tau \psi_{\tau}+i \psi_{\theta}\right] \exp (i \theta) \tag{3.2}
\end{equation*}
$$

( $z=x+i y$ ). The derivatives $\psi_{\tau}$ and $\psi_{\theta}$ are found using the spline-approximation of the grid values of $\psi$.
If the function $\psi$ is the solution of Eq. (2.1), then the values of $x$ and $y$ determined from (3.2) should be independent of the path of integration. This reasoning is used to rationally choose the parameters $\beta_{1}$ and $\beta_{2}$ in (3.1) and control the accuracy of calculations.

In particular, the following formula can be obtained from (3.2):

$$
\begin{equation*}
y=\frac{1}{\nu \tau}\left[\psi \cos \theta+\int_{0}^{\theta}\left(\tau \psi_{\tau}+\psi\right) \sin \theta d \theta\right]+\Omega(\tau) . \tag{3.3}
\end{equation*}
$$

We consider the flow according to the Joukowski-Roshko pattern. In this pattern, $\Omega(\tau)=0$ for $0 \leqslant \tau<1$ and $\Omega(\tau)=$ const $>0$ for $1<\tau \leqslant \tau_{0}$. According to (3.3), for $\sigma \rightarrow 0(\tau \rightarrow 1$ and $\theta \rightarrow 0)$ we have

$$
y \sim I=\frac{1}{\nu_{a}}\left[\psi_{1}+J_{1}+J_{2}\right]+\Omega(\tau), \quad J_{1}=\int_{0}^{\theta} \psi_{1} \theta d \theta, \quad J_{2}=\int_{0}^{\theta} \psi_{1} \theta d \theta,
$$

where $\psi_{1}=\sigma^{-1} \sin \omega$ and $\nu_{a}$ is the value of $\nu$ for $\tau=1\left(\lambda=\lambda_{a}\right)$.
Using (2.3) and (2.4), it is easy to see that

$$
\begin{gathered}
J_{1}=\sigma[\sin \omega-g(\omega) \cos \omega], \quad J_{2}=\alpha \sin \omega \cos \omega-\alpha g(\omega), \quad g(\omega)=\omega, \quad 0 \leqslant \omega<\pi / 2 \quad(\zeta>0) ; \\
g(\omega)=\omega-\pi, \quad \pi / 2<\omega \leqslant \pi \quad(\zeta<0) .
\end{gathered}
$$

It follows that

$$
\begin{aligned}
& I \rightarrow \frac{1}{\nu_{a}}\left(\sigma^{-1}+\sigma+\frac{\alpha \pi}{2}\right) \text { for } \quad \zeta<0, \quad \omega \rightarrow \pi / 2, \\
I \rightarrow & \frac{1}{\nu_{a}}\left(\sigma^{-1}+\sigma-\frac{\alpha \pi}{2}\right)+\left.\Omega(\tau)\right|_{\zeta>0} \text { for } \quad \zeta>0, \quad \omega \rightarrow \pi / 2 .
\end{aligned}
$$

For the quantity $y$ to be continuous on the straight line $\omega=\pi / 2(\zeta=0)$, it is necessary to set $\Omega(\tau)=\alpha \pi / \nu_{a}$ for $\zeta>0$. Thus, for $\psi_{1}=\sigma^{-1} \sin \omega$ (the function $\psi_{1}$ is determined to an accuracy of constant

TABLE 1

| $\mathrm{M}_{a}$ | $H_{1} / h$ | $L_{1} / H_{1}$ | $\left(L_{1} / H_{1}\right)_{1}$ | $L_{1}^{2} / S_{1}$ | $C_{x}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| 0.7 | 2.58882 | 3.90015 | 3.61713 | 4.53994 | 1.73478 |
| 0.8 | 3.93988 | 8.47711 | 7.96622 | 10.1306 | 1.45803 |
| 0.9 | 8.04174 | 27.2457 | 26.2955 | 33.1951 | 1.27772 |
| 0.95 | 16.2770 | 81.1159 | 79.7016 | 99.4350 | 1.21198 |
| 0.98 | 40.9940 | 329.112 | 327.669 | 404.376 | 1.17843 |
| 0.99 | 82.1698 | 937.916 | 938.679 | 1153.00 | 1.16810 |

TABLE 2

| $\mathrm{M}_{a}$ | $H_{2} / h$ | $L_{2} / H_{2}$ | $S_{2} / H_{2}^{2}$ | $S_{2}^{\prime} / H_{2}^{2}$ | $C_{x}$ | $Q H_{2} h^{-1}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.7 | 2.22845 | 1.15456 | 0.98182 | 0.17274 | 1.73565 | 1.73611 |
| 0.8 | 3.35659 | 2.61490 | 2.14113 | 0.47377 | 1.45822 | 1.45891 |
| 0.9 | 6.80670 | 8.61855 | 6.85351 | 1.76504 | 1.27773 | 1.27869 |
| 0.95 | 13.7467 | 25.8366 | 20.3511 | 5.48553 | 1.21198 | 1.21265 |
| 0.98 | 34.6076 | 105.211 | 82.5795 | 22.6313 | 1.17842 | 1.17936 |
| 0.99 | 69.3864 | 300.325 | 235.549 | 64.7756 | 1.16809 | 1.16916 |

factor) we have $y=\alpha \pi / \nu_{a}$ on $A E$. This relationship can be also used to control the calculation accuracy.
We introduce into consideration the cavitation number $Q$ and the drag coefficient of the wedge $C_{x}$ when the latter is exposed to a compressible fluid (gas) in accordance with one of the cavitation schemes considered: $Q=2\left(p_{a}-p_{c}\right) /\left(\rho_{a} V_{a}^{2}\right)$ and $C_{x}=2 X /\left(\rho_{a} V_{a}^{2} h\right)$. Here $V_{a}, \rho_{a}$, and $p_{a}$ are the velocity, density, and pressure of the fluid at an infinitely distant point, $p_{c}$ is the pressure in the cavity, $X$ is the wedge drag, and $h$ is the length of the projection of the wedge onto the $y$ axis $\left(h=2 l \sin \theta_{0}\right.$, where $l$ is the length of the wedge cheek $b c$ ).

The following relationship is valid for the Joukowski-Roshko pattern [11]:

$$
\begin{equation*}
C_{x}=Q H_{2} h^{-1} \tag{3.4}
\end{equation*}
$$

which can be also used to control the accuracy of the results obtained. We note that, for a perfect gas with the ratio of specific heats $\gamma$, for $\mathrm{M}_{c}=1$ we have

$$
Q=\frac{2}{\gamma \mathrm{M}_{a}^{2}}\left[1-\left(\frac{2}{\gamma+1}+\frac{\gamma-1}{\gamma+1} \mathrm{M}_{a}^{2}\right)^{\gamma /(\gamma-1)}\right]
$$

4. Using the above technique, a symmetrical flow of an air-like gas around a wedge was calculated according to the Ryabushinskii and Joukowski-Roshko patterns under the condition that $\mathrm{M}_{c}=1$. Systematic calculations were performed for $\theta_{0}=30,45,60,75$, and $90^{\circ}$ and $M_{a}=0.7,0.8,0.9,0.95,0.98$, and 0.99 (these values of $\theta_{0}$ and $M_{a}$ are called the reference values). A grid obtained by division of each side of the square $\Sigma_{1}$ into 100 equal parts was used. The values of $\psi^{0}$ in seven internal nodes of the grid in the vicinity of the point $A$ were used as the additional boundary values of $\psi$ [we assume that $\psi^{0}=\sigma^{-1 / 2} \cos (\omega / 2)$ for the Ryabushinskii pattern and $\psi^{0}=\sigma^{-1} \sin \omega+f_{2}(\omega)$ for the Joukowski-Roshko pattern]. For all the reference values of $\theta_{0}$ and $M_{a}$, condition (3.4) in problem $B$ was satisfied with an error less than $0.15 \%$.

Some results of the solution of problems $A_{0}$ and $B$ for $\theta_{0}=\pi / 2$ are listed in Tables 1 and 2, respectively ( $h$ is the length of the straight section which forms the front part of the contour of the optimal body).

By approximating the calculation data by the least-squares method, we obtained the dependences $\mathrm{M}_{*}=F_{1}\left(H_{1} / L_{1}, \theta_{0}\right), \mathrm{M}_{*}=F_{2}\left(S_{1} / L_{1}^{2}, \theta_{0}\right), \mathrm{M}_{*}=F_{3}\left(H_{2} / L_{2}, \theta_{0}\right)$, and $\mathrm{M}_{*}=F_{4}\left(H_{2}^{2} / S_{2}^{\prime}, \theta_{0}\right)$, which characterize the solutions of problems A and B for an air-like gas in the domain $\pi / 6 \leqslant \theta_{0} \leqslant \pi / 2,0.7 \leqslant \mathrm{M}_{*} \leqslant 1$ and have

TABLE 3

| Problem A |  |  |  | Problem B |  |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
|  | $i=0$ | $i=1$ | $i=2$ |  | $i=0$ | $i=1$ | $i=2$ |
| $a_{1 i}^{(1)}$ | 0.96658 | 0.00558 | 0.00487 | $a_{1 i}^{(3)}$ | 0.45359 | 0.00061 | 0.00952 |
| $a_{2 i}^{(i)}$ | 0.40108 | -0.09152 | -0.12140 | $a_{2 i}^{(3)}$ | 0.06727 | -0.01306 | -0.08314 |
| $a_{3 i}^{(i)}$ | -0.40975 | 0.66306 | 0.71713 | $a_{3 i}^{(3)}$ | -0.05215 | 0.08993 | 0.18506 |
| $a_{1 i}^{(2)}$ | 1.11427 | 0.00597 | 0.01947 | $a_{1 i}^{(4)}$ | 1.67544 | 0.03082 | -0.04168 |
| $a_{2 i}^{(2)}$ | 0.40026 | -0.10870 | -0.47327 | $a_{2 i}^{(4)}$ | -0.81137 | -2.32541 | 0.11848 |
| $a_{3 i}^{(2)}$ | -0.64369 | 1.37091 | 2.72700 | $a_{3 i}^{(4)}$ | -0.81394 | 4.03693 | -0.83213 |

the following form:

$$
\begin{gather*}
F_{k}\left(t_{k}, \theta_{0}\right)=\left[1+a_{1}^{(k)} t_{k}^{2 / 3}+a_{2}^{(k)} t_{k}^{4 / 3}+a_{3}^{(k)} t_{k}^{2}\right]^{-1}, \quad t_{1}=\frac{H_{1}}{L_{1}}, \quad t_{2}=\frac{S_{1}}{L_{1}^{2}}, \quad t_{3}=\frac{H_{2}}{L_{2}}, \\
a_{n}^{(k)}=a_{n 0}^{(k)}+a_{n 1}^{(k)}\left(\pi / 2-\theta_{0}\right)+a_{n 2}^{(k)}\left(\pi / 2-\theta_{0}\right)^{5}, \quad k=1,2,3, \quad n=1,2,3,  \tag{4.1}\\
F_{4}\left(t_{4}, \theta_{0}\right)=\left[1+a_{1}^{(4)} p+a_{2}^{(4)} p^{2}+a_{3}^{(4)} p^{3}\right]^{-1}, \quad t_{4}=\frac{H_{2}^{2}}{S_{2}^{\prime}}, \quad p=0.1\left(\frac{1}{t_{4}}-\frac{1}{4} \cot \theta_{0}\right)^{-2 / 3}, \\
a_{n}^{(4)}=a_{n 0}^{(4)}+a_{n 1}^{(4)}\left(\pi / 2-\theta_{0}\right)+a_{n 2}^{(4)}\left(\pi / 2-\theta_{0}\right)^{4}, \quad n=1,2,3 .
\end{gather*}
$$

The values of the coefficients $a_{n i}^{(k)}$ are listed in Table 3.
For all the reference values of the parameters $\theta_{0}$ and $M_{a}=M_{*}$, the error of approximation of the numerical data by formulas (4.1) does not exceed $0.05 \%$. For $\theta_{0}=\pi / 2$, in deriving formulas (4.1) we used the calculation results obtained for 12 different values of $M_{a}$ within the range $[0.7,0.995]$, including the reference values; in this case the approximation is more accurate. In particular, the relationship

$$
\begin{equation*}
F_{1}\left(t_{1}, \pi / 2\right)=\left[1+0.96658 t_{1}^{2 / 3}+0.40108 t_{1}^{4 / 3}-0.40975 t_{1}^{2}\right]^{-1} \tag{4.2}
\end{equation*}
$$

where $t_{1}=H_{1} / L_{1}$, approximates the numerical data with an error less than $0.006 \%$.
Figure 2 shows the dependence of $\mathrm{M}_{*}$ on $t_{1}=H_{1} / L_{1}$ (curves $1-3$ for $\theta_{0}=\pi / 2, \pi / 4$, and $\pi / 6$ ) and on $\theta_{0}$ (curves 4-6 for $t_{1}=0.2,0.1$, and 0.05 ). The dependences of $M_{*}$ on $t_{k}$ and $\theta_{0}$ for $k=2,3$, and 4 are similar in shape. As $t_{k}$ decreases (as $M_{*}$ approaches unity), the dependence of $M_{*}$ on $\theta_{0}$ becomes weaker $\left(\partial F_{k}\left(t_{k}, \theta_{0}\right) / \partial \theta_{0} \rightarrow 0\right.$ for $\left.t_{k} \rightarrow 0\right)$. Each of the functions $F_{k}\left(t_{k}, \theta_{0}\right)$ is monotonically decreasing relative to $t_{k}$ and monotonically increasing relative to $\theta_{0}$, at least for $\pi / 6 \leqslant \theta_{0} \leqslant \pi / 2$ and the values of $t_{k}$ that ensure satisfaction of the condition $F_{k}\left(t_{k}, \theta_{0}\right) \geqslant 0.7$.

In solving problem $A_{0}$ for a perfect gas with the ratio of specific heats $\gamma$, Fisher [3] used the equation

$$
\psi_{\mu \mu}+\psi_{\theta \theta}+g \psi_{\mu}=0, \quad \mu=\int_{1}^{\lambda} \frac{\sqrt{1-\mathrm{M}^{2}}}{\lambda} d \lambda, \quad g=-\frac{\gamma+1}{2} \frac{\mathrm{M}^{4}}{\left(1-\mathrm{M}^{2}\right)^{3 / 2}}
$$

The boundary-value problem is solved for the function $\chi=\psi-\psi^{0}$, where $\psi^{0}=\operatorname{Im}\left\{i\left[\theta+i\left(\mu-\mu_{a}\right)\right]\right\}^{-1 / 2}$ and $\mu_{a}$ is the value of $\mu$ for $\lambda=\lambda_{a}$. Calculations were performed for $\gamma=1.4$ and three values of $M_{a}$. According to [3], we have $L_{1} / H_{1}=4.30,7.87$, and 14.36 for $M_{a}=0.72,0.80$, and 0.86 , respectively. The method of the present paper yields $L_{1} / H_{1}=4.49,8.48$, and 15.70 for the same values of $M_{a}$. This difference in the results can be explained by the use of a rather rough grid in [3] and by the need to eliminate a part of the semi-infinite region of variation of the parameters $\mu$ and $\theta(-\infty<\mu \leqslant 0)$.

The method used by Schwendeman et al. [4] to solve problem $A_{0}$ is close to the method of the present


Fig. 2
paper. The results are plotted as $H_{1} / L_{1}$ versus $\mathrm{M}_{a}$ for $\gamma=1.4$, which is in good agreement with our points.
For a perfect gas with the ratio of specific heats $\gamma$, the following formula is obtained in solving problem $\mathrm{A}_{0}$ on the basis of the transonic theory of small perturbations [4]:

$$
\begin{equation*}
\frac{1-\mathrm{M}_{a}^{2}}{\mathrm{M}_{a}^{4}}=K\left(H_{1} / L_{1}\right)^{2 / 3}, \quad K=\left[\pi \frac{\gamma+1}{2} \frac{\Gamma(5 / 6)}{\Gamma(4 / 3)}\right]^{2 / 3} . \tag{4.3}
\end{equation*}
$$

The values of $L_{1} / H_{1}$, calculated in accordance with (4.3) for $\gamma=1.4$ and $K=1.93353$, are listed in Table 1 as $\left(L_{1} / H_{1}\right)_{1}$. The difference between the values of $L_{1} / H_{1}$ and $\left(L_{1} / H_{1}\right)_{1}$ decreases monotonically as $\mathrm{M}_{a}$ increases from $8 \%$ for $\mathrm{M}_{a}=0.7$ to $0.08 \%$ for $\mathrm{M}_{a}=0.99$.

In accordance with (4.3), the following asymptotic relationship is valid for an exact solution of problem $\mathrm{A}_{0}$ :

$$
\begin{equation*}
1-\mathrm{M}_{a}^{2} \sim K\left(H_{1} / L_{1}\right)^{2 / 3}, \quad \mathrm{M}_{a} \rightarrow 1 \tag{4.4}
\end{equation*}
$$

At the same time, according to (4.2) we have

$$
1-\mathrm{M}_{a}^{2} \sim 2 a_{10}^{(1)} t_{1}^{2 / 3}=1.93316\left(H_{1} / L_{1}\right)^{2 / 3}, \quad \mathrm{M}_{a} \rightarrow 1, \quad \gamma=1.4 .
$$

Thus, the coefficient $a_{10}^{(1)}$ found as a result of approximation of numerical data, differs only by $0.02 \%$ from the value that ensures satisfaction of the asymptotic relationship (4.4) for $\gamma=1.4$. This supports the reliability of our results.

Brutyan and Lyapunov [5] considered a problem similar to problem A. The solution of the problem of flow of an air-like gas around a wedge according to the Ryabushinskii pattern was constructed by the finite-difference method in the physical plane for prescribed parameters $\beta=l \cos \theta_{0} / L_{1}$ and $\mathrm{M}_{a}$. The plots for $\mathrm{M}_{*}$ versus $S_{1} / L_{1}^{2}$ for $\beta=0.2$ and $\theta_{0}$ versus $\beta$ for $Q=0.5,0.9$, and 1.5 are presented in [5] for an optimal body relative to $\mathrm{M}_{*}$.

Mackie [13] was the first to study the problem of a symmetrical gas flow around a wedge according to the Joukowski-Roshko pattern at supersonic velocity on the free surface, which forms the basis of the solution of problem B. Using the method of separation of variables in combination with the method of contour integrals, Mackie derived analytical relations for the stream function $\psi$, which have the form of series whose terms contain hypergeometric functions. The flow parameters based on these relations were not calculated.

The same problem was considered by Shcherbakov [6] who constructed a function $\psi_{0}$ that describes the behavior of the stream function $\psi(\lambda, \theta)$ in the vicinity of the singular point and vanishes at the boundary of the domain of variation of the velocity hodograph. The function $\chi=\psi-\psi_{0}$ satisfies the equation $L \chi=-L \psi_{0}$ ( $L \psi=0$ is the Chaplygin equation) and homogeneous boundary conditions. To find it, we use an approach based on the construction of the Green function. As a result, $\chi$ is found as a series whose terms contain multipliers, which are hypergeometric functions, and also simple and iterated integrals with integrands which contain the same functions. The resultant representation $\psi=\psi_{0}+\chi$ is used to calculate the characteristics of the flow considered. The main result of $[6]$ is the plot of $H_{2} / 2 L_{2}$ versus $\left|\theta_{0}\right|\left(0 \leqslant\left|\theta_{0}\right| \leqslant 90^{\circ}\right)$ for $\mathrm{M}_{*}=$
$0.3, ~ U .4, \ldots, 0.9$ for an air-like gas.
The method of the present paper yields results which are in reasonable agreement with the plots presented in $[5,6]$.
5. Thus, the basic result of the present paper is analytical functions of the critical Mach number $M_{*}$ versus $t_{k}$ and $\theta_{0}$, which were found for the first time and characterize the solution of problems A and B for an air-like gas in the range of arguments which is most important for practice. We note that the function $F_{1}\left(t_{1}, \theta_{0}\right)$ for $\theta_{0}<\pi / 2$ and also the functions $F_{2}\left(t_{2}, \theta_{0}\right)$ and $F_{4}\left(t_{4}, \theta_{0}\right)$ have not yet been studied.

Obviously, for arbitrary plane symmetrical bodies of finite length, which satisfy condition (1.2) and are exposed to an attached symmetrical potential flow of an air-like gas, the following relations are valid:

$$
\begin{equation*}
\mathrm{M}_{*} \leqslant F_{1}\left(H_{1} / L_{1}, \theta_{0}\right), \quad \mathrm{M}_{*} \leqslant F_{2}\left(S_{1} / L_{1}^{2}, \theta_{0}\right) . \tag{5.1}
\end{equation*}
$$

Similarly, for arbitrary plane symmetrical semi-infinite bodies obtained by means of deformation of the front part of a rectangular band, which satisfy condition (1.2) and are exposed to an attached potential flow of an air-like gas, the following relations are valid:

$$
\begin{equation*}
\mathrm{M}_{*} \leqslant F_{3}\left(H_{2} / L_{2}, \theta_{0}\right), \quad \mathrm{M}_{*} \leqslant F_{4}\left(H_{2}^{2} / S_{2}^{\prime}, \theta_{0}\right) . \tag{5.2}
\end{equation*}
$$

A strict equality in (5.1) and (5.2) is fulfilled only for optimal bodies relative to $M_{*}$.
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